

## 12-Channel Self Calibration Capacitive Touch Sensor

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### SPECIFICATION V1.3

Drafter	Director	Review	Marketing	QA	Approval

## ■ Revision History

Rev.	Description of change	Date	Originator
1.0	Initial Release	06.11.15	BM KIM
1.1	Revision Flow chart , Appending 'Wait 100ms'	09.06.04	SB CHEONG
1.2	Revision Unused CS pin -> Connect with GND	10.02.10	KD PARK
1.3	Appending MLF package Appending MLF package Dimension Appending MLF package marking spec	10.02.10	KDPARK

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 1 Specification

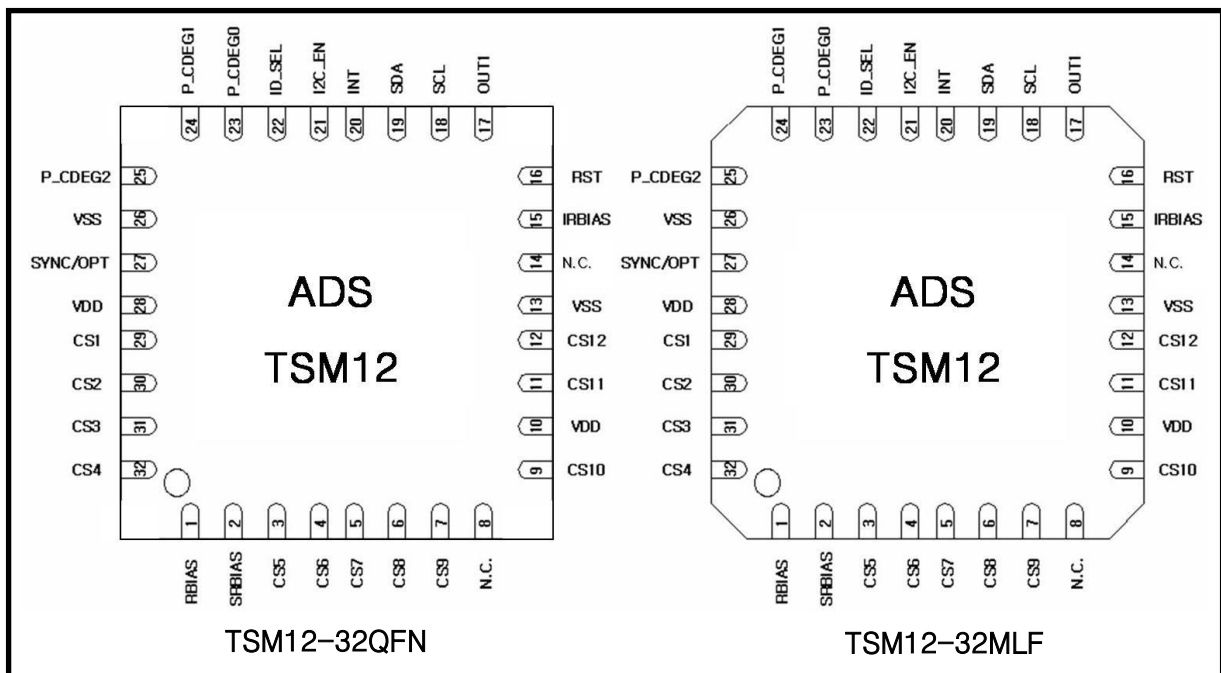
#### 1.1 General Feature

- 12-Channel capacitive sensor with auto sensitivity calibration
- Selectable output operation (single mode / multi-mode)
- Independently adjustable in 8 step sensitivity
- Sync function for multi chip application
- Touch intensity can be detectable within 3 steps (Low, Middle and High)
- Adjustable internal frequency with external resister
- Adjustable response time and interrupt level by the control registers
- I2C serial interface
- Embedded high frequency noise elimination circuit
- IDLE mode to save the consumption
- Embedded power key function on channel 1 for mobile phone application
- RoHS compliant 32QFN, 32MLF packages

#### 1.2 Application

- Mobile application (mobile phone / PDA / PMP etc)
- Membrane switch replacement
- Sealed control panels, keypads
- Door key-lock matrix application
- Touch screen replacement application

#### 1.3 Package (32QFN, 32MLF)



Drawings not to scale

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 2 Pin Description (32QFN, 32MLF)

PIN No.	Name	I/O	Description	Protection
1	RBIAS	Analog Input	Internal bias adjust input	VDD/GND
2	SRBIAS	Analog Input	IDLE Mode Internal bias adjust input	VDD/GND
3	CS5	Analog Input	CH5 capacitive sensor input	VDD/GND
4	CS6	Analog Input	CH6 capacitive sensor input	VDD/GND
5	CS7	Analog Input	CH7 capacitive sensor input	VDD/GND
6	CS8	Analog Input	CH8 capacitive sensor input	VDD/GND
7	CS9	Analog Input	CH9 capacitive sensor input	VDD/GND
8	N.C.	–	No Connection	–
9	CS10	Analog Input	CH10 capacitive sensor input	VDD/GND
10	VDD	Digital Input	–	VDD/GND
11	CS11	Analog Input	CH11 capacitive sensor input	VDD/GND
12	CS12	Analog Input	CH12 capacitive sensor input	VDD/GND
13	VSS	Ground	Supply ground	VDD
14	NC	–	No Connection	–
15	IRBIAS	Analog Input	Internal I2C clk frequency adjust input	VDD/GND
16	RST	Digital Input	System reset (High reset)	VDD/GND
17	OUT1	Digital Output	CH1 output (Open drain)	VDD/GND
18	SCL	Digital Input	I2C clock input	VDD/GND
19	SDA	Digital Input/Output	I2C data (Open drain)	VDD/GND
20	INT	Digital Output	Interrupt output (Open drain)	VDD/GND
21	I2C_EN	Digital Input	I2C enable(Low enable)	VDD/GND
22	ID_SEL	Digital Input	I2C address selection	VDD/GND
23	P_CDEG0	Digital Input	Ch1 sensitivity selection bit0	VDD/GND
24	P_CDEG1	Digital Input	Ch1 sensitivity selection bit1	VDD/GND
25	P_CDEG2	Digital Input	Ch1 sensitivity selection bit2	VDD/GND
26	VSS	Digital Input	–	VDD/GND
27	SYNC/OPT	Digital Input/Output	Output mode selection (Single Output / Multi Output <b>Note 1</b> ) Sync pulse input /output	VDD/GND
28	VDD	Power	Power (2.5V~5.0V)	GND
29	CS1	Analog Input	CH1 capacitive sensor input	VDD/GND
30	CS2	Analog Input	CH2 capacitive sensor input	VDD/GND
31	CS3	Analog Input	CH3 capacitive sensor input	VDD/GND
32	CS4	Analog Input	CH4 capacitive sensor input	VDD/GND

**Note 1 :** Refer to 6.3 SYNC/OPT implementation

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 3 Absolute Maximum Rating

Battery supply voltage	5.0V
Maximum voltage on any pin	VDD+0.3
Maximum current on any PAD	100mA
Power Dissipation	800mW
Storage Temperature	-50 ~ 150℃
Operating Temperature	-20 ~ 75℃
Junction Temperature	150℃

**Note** Unless any other command is noted, all above are operated in normal temperature.

### 4 ESD & Latch-up Characteristics

#### 4.1 ESD Characteristics

Mode	Polarity	Max	Reference
H.B.M	Pos / Neg	2000V	VDD
		2000V	VSS
		2000V	P to P
M.M	Pos / Neg	200V	VDD
		200V	VSS
		200V	P to P
C.D.M	Pos / Neg	500V	DIRECT
		800V	

#### 4.2 Latch-up Characteristics

Mode	Polarity	Max	Test Step
I Test	Positive	200mA	25mA
	Negative	-200mA	
V supply over 5.0V	Positive	8.0V	1.0V

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 5 Electrical Characteristics

■  $V_{DD}=3.3V$ ,  $R_B=510k$ , Sync Mode ( $R_{sync} = 2M\Omega$ ) (Unless otherwise noted),  $T_A = 25^\circ C$

Characteristics	Symbol	Test Condition	Min	Typ	Max	Units
Operating supply voltage	$V_{DD}$		2.5	3.3	5.0	V
Current consumption <b>Note1</b>	$I_{DD}$	$V_{DD}= 3.3V$ $R_B=510k$ $R_{SB}=0$	–	80	130	$\mu A$
		$V_{DD}= 5.0V$ $R_B=510k$ $R_{SB}=0$	–	200	315	
		$V_{DD}= 3.3V$ $R_B=510k$ $R_{SB}=3M$	–	7	–	
		$V_{DD}= 5.0V$ $R_B=510k$ $R_{SB}=3M$	–	15	–	
	$I_{DD\_I2C}$	$V_{DD}= 3.3V$ $R_B=510k$ $R_{I2C}=20k$	–	1.5	–	mA
		$V_{DD}= 5.0V$ $R_B=510k$ $R_{I2C}=30k$	–	2.3	–	
		IDD_I2C Disable	–	–	1	$\mu A$
Output maximum sink current	$I_{OUT}$	$T_A = 25^\circ C$	–	–	4.0	mA
Sense input capacitance range <b>Note2</b>	$C_S$		–	10	100	pF
Sense input resistance range	$R_S$		–	200	1000	$\Omega$
Minimum detective capacitance difference	$\Delta C$	$C_S = 10pF$ , $C_{DEG} = 200pF$ (I2C default sensitivity select)	0.2	–	–	pF
Output impedance (open drain)	$Z_o$	$\Delta C > 0.2pF$ , $C_S = 10pF$ , (I2C default sensitivity select)	–	12	–	$\Omega$
		$\Delta C < 0.2pF$ , $C_S = 10pF$ , (I2C default sensitivity select)	–	30M	–	
Self calibration time after system reset	$T_{CAL}$	$V_{DD} = 3.3V$ $R_B = 510k$	–	100	–	ms
		$V_{DD} = 5.0V$ $R_B = 510k$	–	80	–	
Recommended bias resistance range <b>Note3</b>	$R_B$	$V_{DD} = 3.3V$	200	510	820	k $\Omega$
		$V_{DD} = 5.0V$	330	620	1200	
Maximum bias capacitance	$C_{B\_MAX}$		–	820	1000	pF
Recommended sync resistance range	$R_{SYNC}$		1	2	20	M $\Omega$

**Note 1** : In case of SCL frequency is 500kHz.

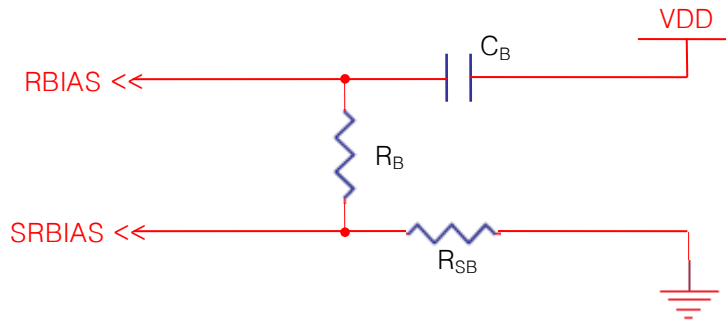
**Note 2** : The sensitivity can be increased with lower  $C_S$  value.

The recommended value of  $C_S$  is 10pF when using 3T PC(Poly Carbonate) cover and 10 mm x 7 mm touch pattern.

**Note 3** : The lower  $R_B$  is recommended in noisy condition.

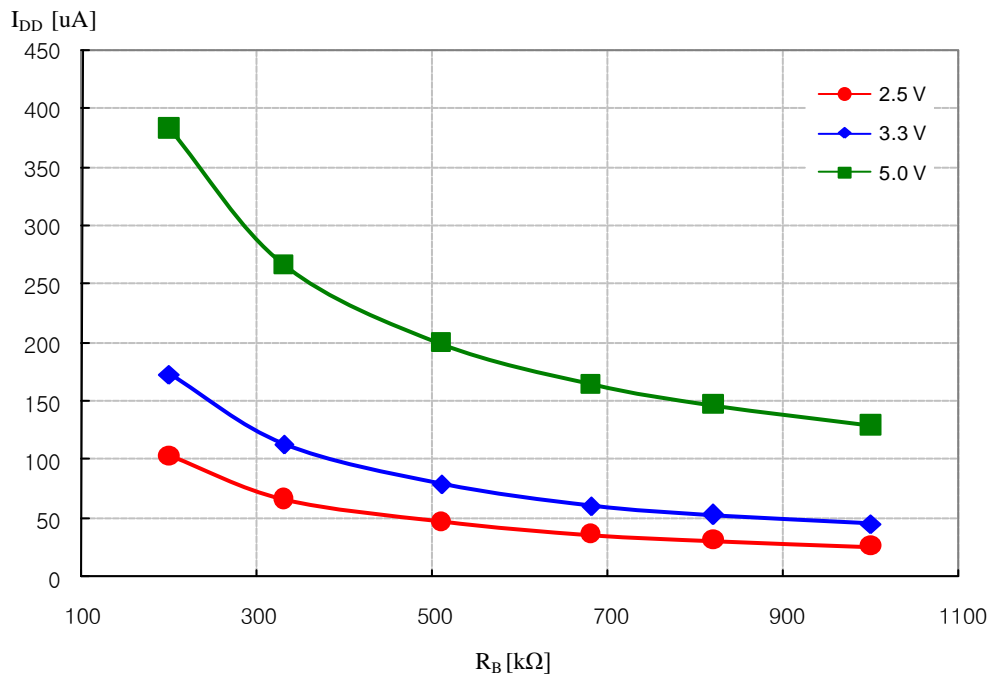
### 6 Implementation of TSM12

#### 6.1 RBIAS & SRBIAS implementation



The RBIAS is connecting to the resistor to decide the oscillator and internal bias current. The sensing frequency, internal clock frequency and current consumption are therefore able to be adjusted with  $R_B$ . A voltage ripple on RBIAS can make critical internal error, so  $C_B$  is connected to the VDD (not GND) is recommended. (The typical value of  $C_B$  is 820pF and the maximum Value is 1nF.)

The  $R_{SB}$  should be connected as above figure when the TSM12 operates in IDLE Mode to save the current consumption. In this case, the consumption depends on the sum of the serial resistors and the response time might be longer.

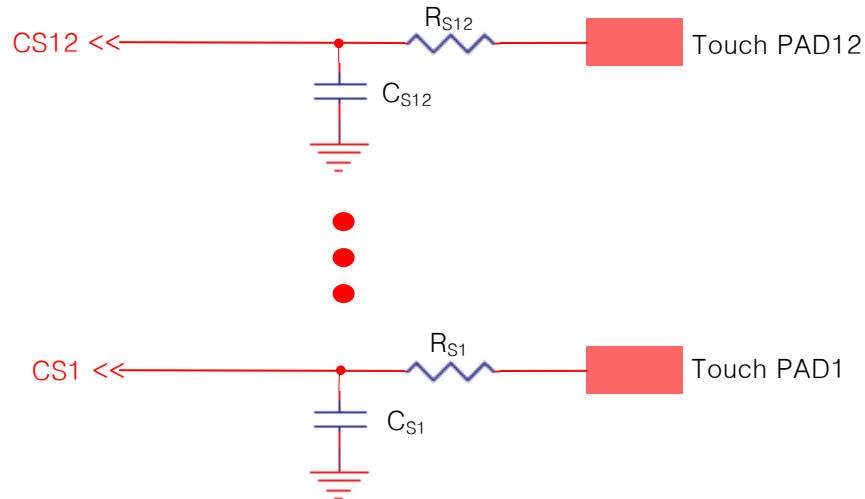


Normal operation current consumption curve (Pin21 I2C\_EN is High)

The current consumption curve of TSM12 is represented in accordance with  $R_B$  value as above. The lower  $R_B$  requires more current consumption but it is recommended in noisy application. For example, refrigerator, air conditioner and so on.

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

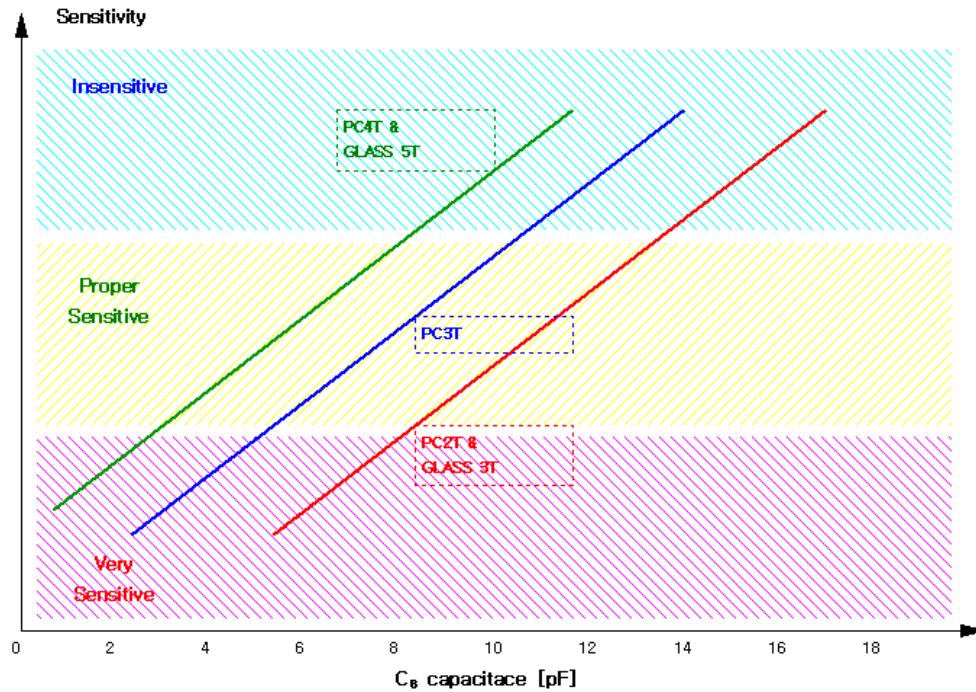
### 6.2 CS implementation



The TSM12 has basically eight steps sensitivity, which is available to control with internal register by I2C interface. The parallel capacitor  $C_{S1}$  is added to CS1 and  $C_{S12}$  to CS12 to adjust sensitivity. The sensitivity will be increased when smaller value of  $C_S$  is used. (Refer to the below Sensitivity Example Figure) It could be useful in case detail sensitivity mediation is required. The internal touch decision process of each channel is separated from each other. The twelve channel touch key board application can therefore be designed by using only one TSM12 without coupling problem. The  $R_S$  is serial connection resistor to avoid mal-function from external surge and ESD. (It might be optional.) From  $200\Omega$  to  $1k\Omega$  is recommended for  $R_S$ . The size and shape of PAD might have influence on the sensitivity. The sensitivity will be optimal when the size of PAD is approximately an half of the first knuckle (it's about  $10\text{ mm} \times 7\text{ mm}$ ). The connection line of CS1 ~ CS12 to touch PAD is recommended to be routed as short as possible to prevent from abnormal touch detect caused by connection line. The unused CS pin must be connected with the ground to prevent the unpredictable mal-function that occurred in the floating CS pin.



## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

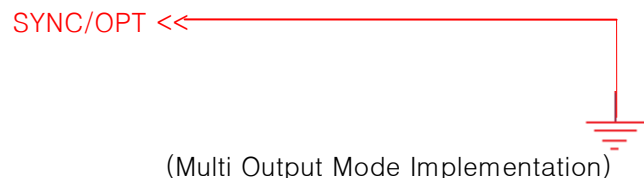
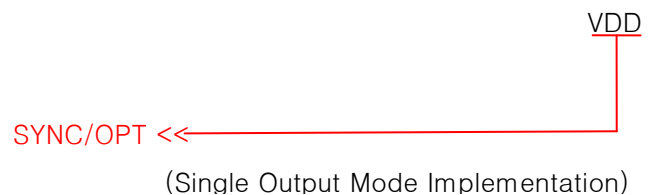


Sensitivity example figure with default sensitivity selection

### 6.3 SYNC/OPT implementation

#### 6.3.1 Output Mode Option

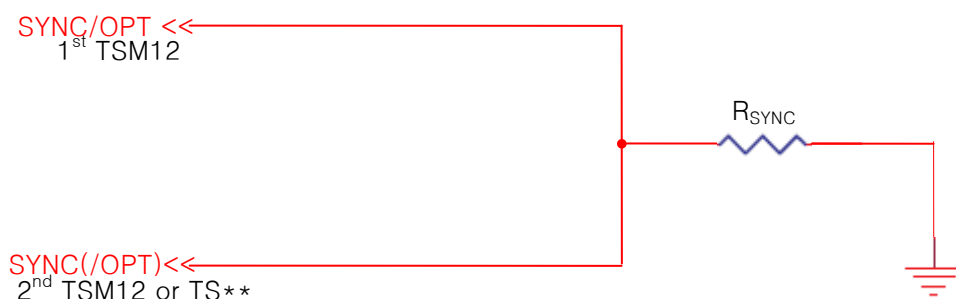
This pin will be assigned for the output mode option selection. It will decide that TSM12 is working on single or multi touch detection mode. It should be implemented as below for these.



## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 6.3.2 Multi Chip Application

Over two TSM12 can work on the one application at the same time thanks to SYNC function with this pin. The SYNC pulse prevents over two sensing signal from interfering with each other.  $R_{SYNC}$  is pull-down resistor of SYNC/OPT pin. Too big value of  $R_{SYNC}$  makes the SYNC pulse falling delay, and too small value of  $R_{SYNC}$  makes rising delay. Typical value of  $R_{SYNC}$  is 2M $\Omega$ . The Sync pin should be implemented as below. The TSM12 can also be used with the other TSxx series by employing this SYNC function. The TSM12 could only operate on multi output mode in this configuration.



### 6.4 P\_CDEG2 , P\_CDEG1, P\_CDEG0 implementation

The P\_CDEG0, 1 and 2 are only for the CS1 to control the sensitivity. The sensitivity of channel 1 will be controlled by the register (refer to the “sensitivity control register” chapter) same as the other channel if the P\_CDEG(2:0) value is 011. But it should be fixed as following table if the P\_CDEG(2:0) value is not 011.

**The sensitivity table of channel 1**

P_CDEG(2:0)	Sensitivity of Channel 1 (@Cs = 0pF)
011	Respect the register value (refer to the I2C register description)
000	14~16T
001	12~14T
010	10~12T
100	7~9T
101	6~8T
110	5~7T
111	3~5T

Note 1: The unit T represents the thickness (mm) of a panel in case of poly-carbonate.

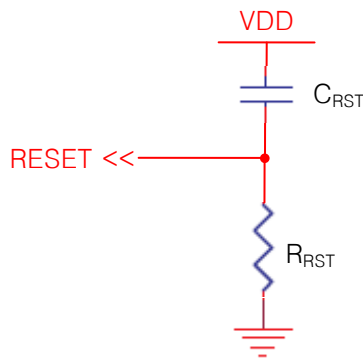
Note 2: The above table data is compatible with a pad size that is approximately an half of the first knuckle. (it's about 10 mm x 7 mm)

The channel 1 provides the output with two ways whether the I2C or the out1 (pin17) directly.

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

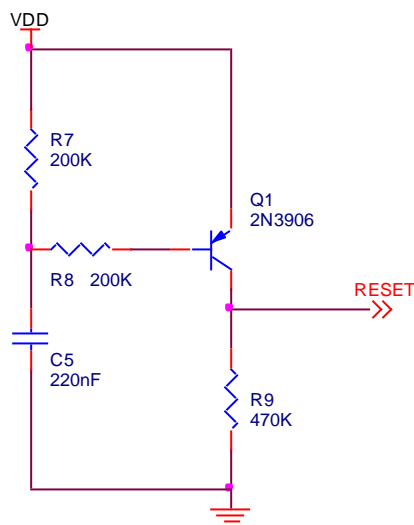
### 6.5 RESET implementation

TSM12 has internal data latches, so initial state of these latches must be reset by external reset pulse before normal operation starts. The reset pulse can be controlled by host MCU directly or other reset device. If not, the circuit should be composed as below figure. The reset pulse must have high pulse duration about a few msec to cover power VDD rising time. The recommended value of  $R_{RST}$  and  $C_{RST}$  are 330K $\Omega$  and 100nF.



Recommended reset circuits 1

The better performance is warranted with below reset circuit. The Q1 is turned on and makes reset pulse when power is on and VDD is raised to operating voltage. After a few msec (duration time is determined by R7, R8, C5), Q1 is turned off and TSM12 can be operated with normal sensitivity.



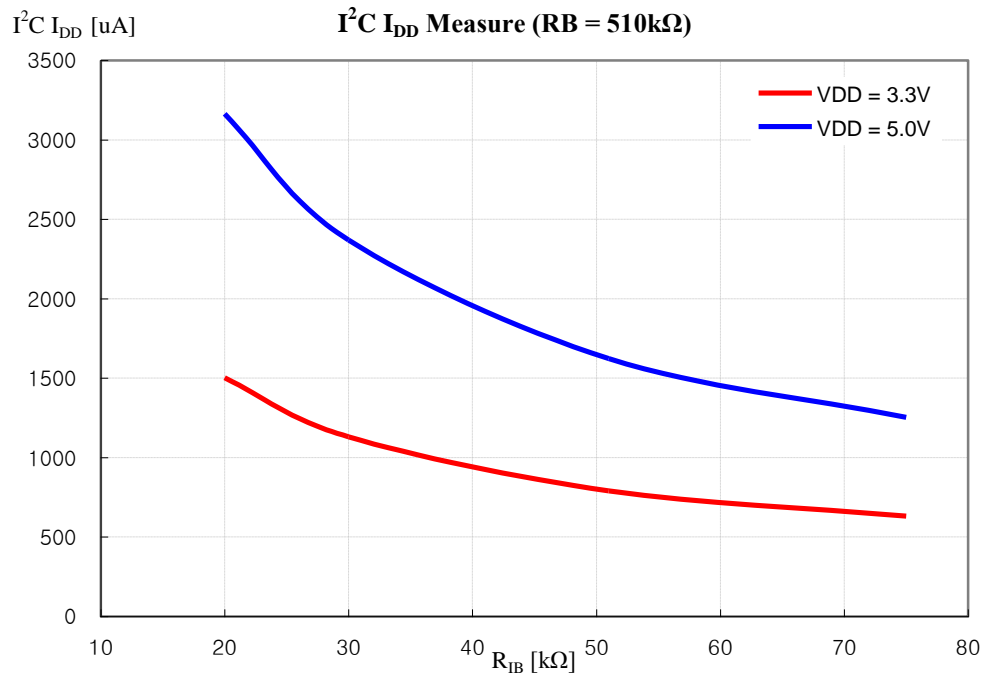
Recommended reset circuits 2

### 7 I<sup>2</sup>C Interface

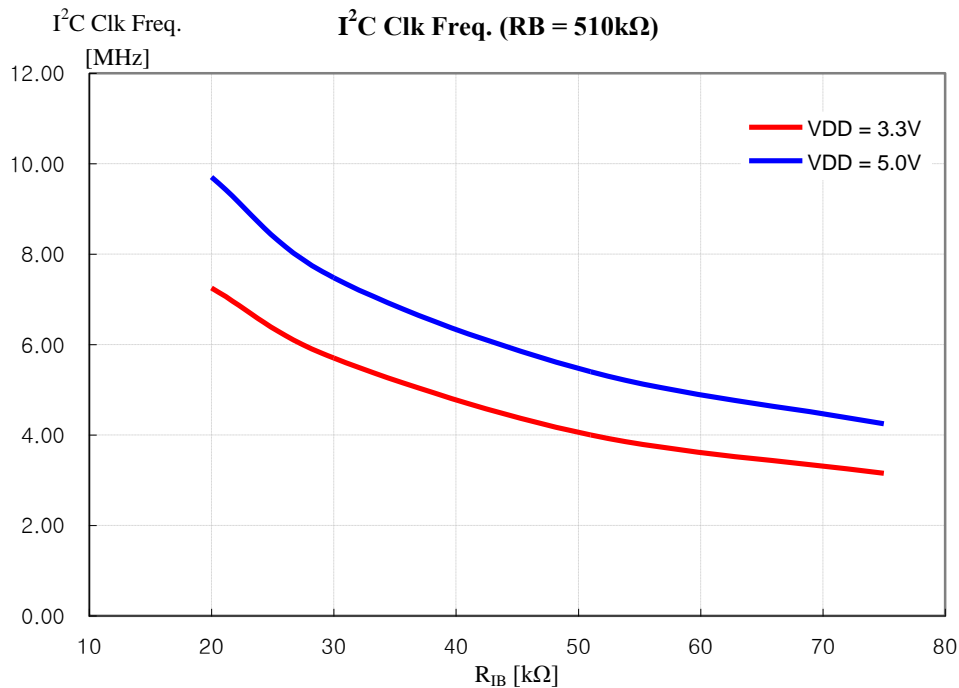
#### 7.1 IRBIAS Implementation



The  $R_{IB}$  is only charged in making the I2C internal clock and should be implemented as above figure. The smaller  $R_{IB}$  will increase the I2C internal clock frequency and current consumption. (Refer to the following consumption curve)



I2C Block operation current consumption curve

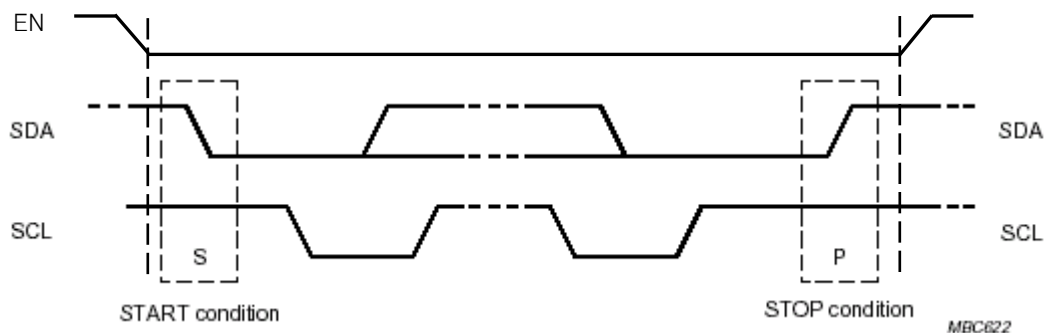


I2C clock frequency curve

## 7.2 Start & Stop Condition

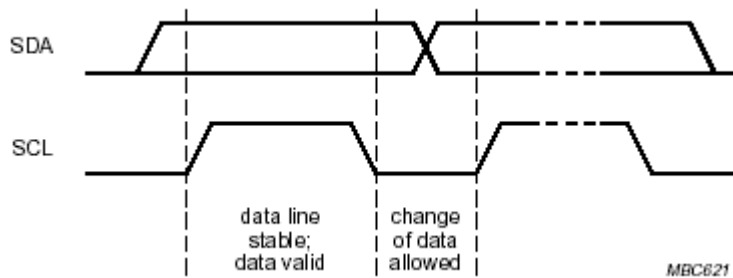
- Start Condition (S)
- Stop Condition (P)
- Repeated Start (Sr)

The EN (Pin21) should be low before START condition and be high after STOP condition.



### 7.3 Data validity

The SDA should be stable when the SCL is high and the SDA can be changed when the SCL is low.

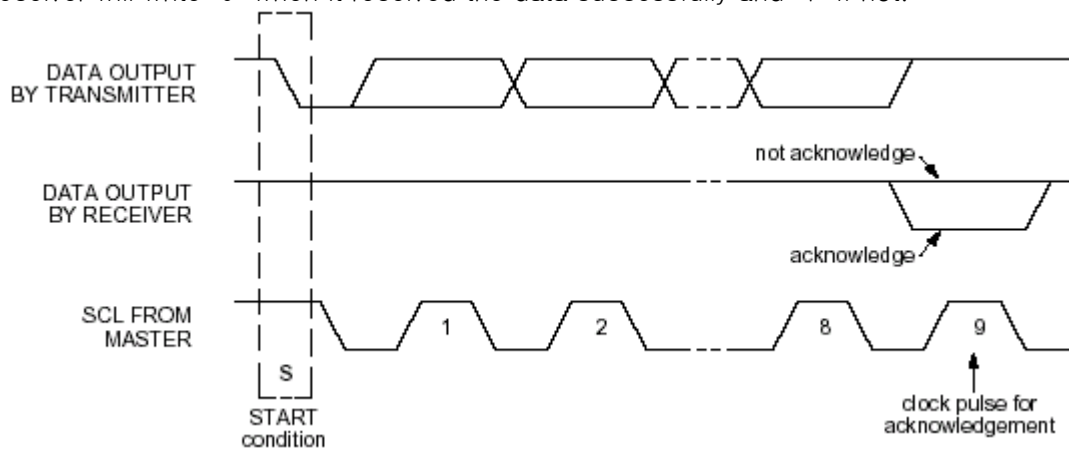


### 7.4 Byte Format

The byte structure is composed with 8Bit data and an acknowledge signal.

### 7.5 Acknowledge

It is a check bit whether the receiver gets the data from the transmitter without error or not. The receiver will write '0' when it received the data successfully and '1' if not.



### 7.6 First Byte

#### 7.6.1 Slave Address

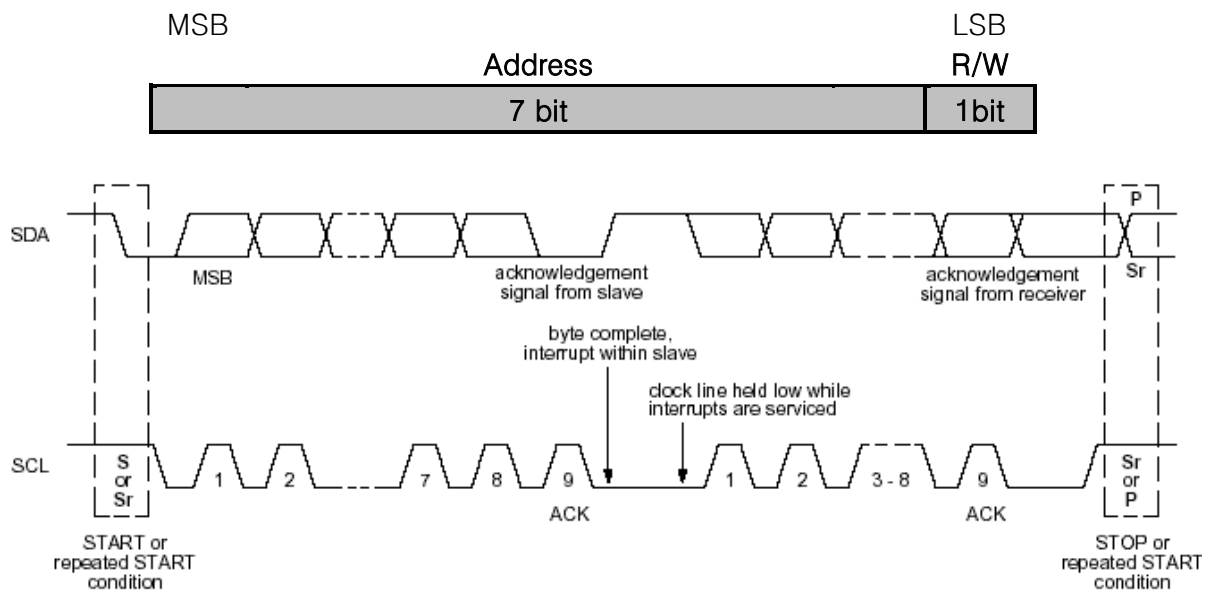
It is the first byte from the start condition. It is used to access the slave device.

TSM12 Chip Address : 7bit

ID_SEL	Address
GND	0xD0
VDD	0xF0

#### 7.6.2 R/W

The direction of data is decided by the bit and it follows the address data.

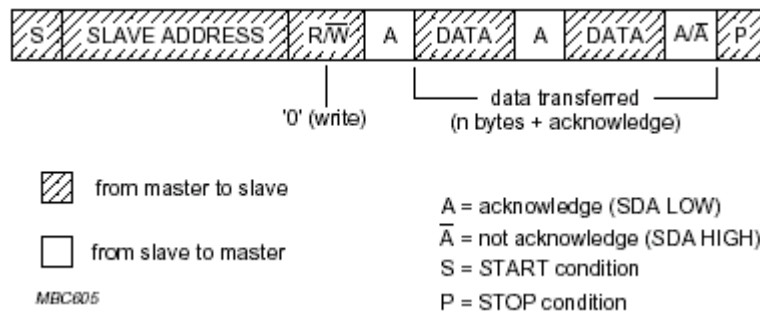


### 7.7 Transferring Data

#### 7.7.1 Write Operation

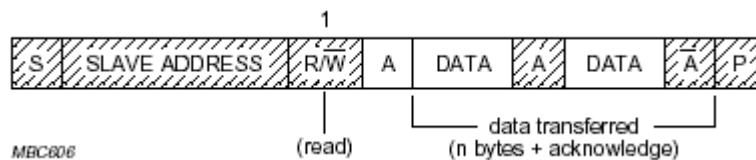
The byte sequence is as follows:

- the first byte gives the device address plus the direction bit (R/W = 0).
- the second byte contains the internal address of the first register to be accessed.
- the next byte is written in the internal register. Following bytes are written in successive internal registers.
- the transfer lasts until stop conditions are encountered.
- the TSM12 acknowledges every byte transfer.

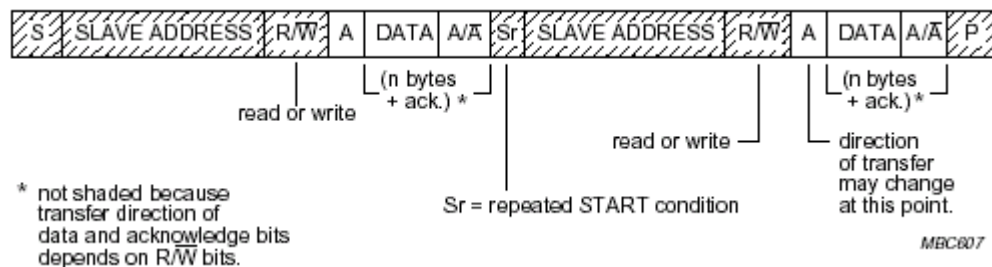


#### 7.7.2 Read Operation

The address of the first register to read is programmed in a write operation without data, and terminated by the stop condition. Then, another start is followed by the device address and R/W= 1. All following bytes are now data to be read at successive positions starting from the initial address.



#### 7.7.3 Read/Write Operation





## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

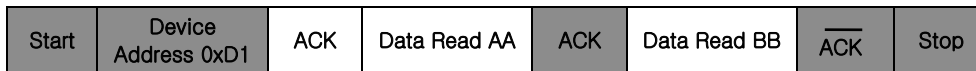
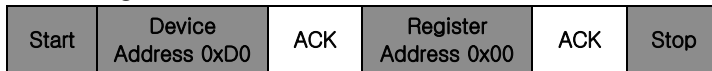
### 7.8 I<sup>2</sup>C write and read operations in normal mode

The following figure represents the I<sup>2</sup>C normal mode write and read registers.

Write register 0x00 to 0x01 with data AA and BB



Read register 0x00 and 0x01



## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8 TSM12 Register List

- ◀ Note: The unused bits (defined as reserved) in I<sup>2</sup>C registers must be kept to zero.
- ◀ Note: The bit0 and bit1 of CTRL2 register must be written by 0b11 after power on during an initialize phase. (Refer to the chapter 9. initialize flow)
- ◀ Note: HS (High Sensitivity) / MS (Middle Sensitivity) / LS (Low Sensitivity)
- ◀ Note: Low Output (light touch) / Middle Output (middle touch) / High Output (hard touch)

#### 8.1 I<sup>2</sup>C Register Map

Name	Addr. (Hex)	Reset Value (Bin)	Register Function and Description							
			Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Sensitivity1	02h	1011 1011	Ch2HL		Ch2M		Ch1HL		Ch1M	
Sensitivity2	03h	1011 1011	Ch4HL		Ch4M		Ch3HL		Ch3M	
Sensitivity3	04h	1011 1011	Ch6HL		Ch6M		Ch5HL		Ch5M	
Sensitivity4	05h	1011 1011	Ch8HL		Ch8M		Ch7HL		Ch7M	
Sensitivity5	06h	1011 1011	Ch10HL		Ch10M		Ch9HL		Ch9M	
Sensitivity6	07h	1011 1011	Ch12HL		Ch12M		Ch11HL		Ch11M	
CTRL1	08h	0010 0010	MS		FTC		ILC		RTC	
CTRL2	09h	0000 01XX	0	0	0	0	SRST	IDLE	1	1
Ref_rst1	0Ah	1111 1110	Ch8	Ch7	Ch6	Ch5	Ch4	Ch3	Ch2	Ch1
Ref_rst2	0Bh	0000 1111	0	0	0	0	Ch12	Ch11	Ch10	Ch9
Ch_hold1	0Ch	1111 1110	Ch8	Ch7	Ch6	Ch5	Ch4	Ch3	Ch2	Ch1
Ch_hold2	0Dh	0000 1111	0	0	0	0	Ch12	Ch11	Ch10	Ch9
Cal_hold1	0Eh	0000 0000	Ch8	Ch7	Ch6	Ch5	Ch4	Ch3	Ch2	Ch1
Cal_hold2	0Fh	0000 0000	0	0	0	0	Ch12	Ch11	Ch10	Ch9
Output1	10h	0000 0000	OUT4		OUT3		OUT2		OUT1	
Output2	11h	0000 0000	OUT8		OUT 7		OUT6		OUT5	
Output3	12h	0000 0000	OUT12		OUT11		OUT10		OUT9	

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8.2 Sensitivity Control Register

#### Sensitivity1

#### Channel 1 & 2 Sensitivity Control

Address (hex): 02h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch2HL	Ch2M[2:0]			Ch1HL	Ch1M[2:0]		

#### Description

The sensitivity of channel 1 and 2 are adjustable by Sensitivity\_1 register. ChxM[2:0] allows various middle sensitivity and also the high and low sensitivities are decided with ChxHL.

Bit name	Reset	Function
ChxM[2:0]	011	Middle sensitivity T (= thickness of PC) @Cs = 0pF <div style="display: flex; justify-content: space-between;"> <div>                         000: 14~16T                          001: 12~14T                          010: 10~12T                          011: 08~10T                     </div> <div>                         100: 7~9T                          101: 6~8T                          110: 5~7T                          111: 3~5T                     </div> </div>
ChxHL	1	High and Low sensitivity selection for channel x 0: HS = MS - (MS * 0.2) LS = MS + (MS * 0.2) 1: HS = MS - (MS * 0.3) LS = MS + (MS * 0.3)

#### Sensitivity2

#### Channel 3 & 4 Sensitivity Control

Address (hex): 03h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch4HL	Ch4M[2:0]			Ch3HL	Ch3M[2:0]		

#### Description

The sensitivity of channel 3 and 4 are adjustable by Sensitivity\_2 register. ChxM[2:0] allows various middle sensitivity and also the high and low sensitivities are decided with ChxHL.

Bit name	Reset	Function
ChxM[2:0]	011	Middle sensitivity T (= thickness of PC) @Cs = 0pF <div style="display: flex; justify-content: space-between;"> <div>                         000: 14~16T                          001: 12~14T                          010: 10~12T                          011: 08~10T                     </div> <div>                         100: 7~9T                          101: 6~8T                          110: 5~7T                          111: 3~5T                     </div> </div>
ChxHL	1	High and Low sensitivity selection for channel x 0: HS = MS - (MS * 0.2) LS = MS + (MS * 0.2) 1: HS = MS - (MS * 0.3) LS = MS + (MS * 0.3)

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### Sensitivity3

### Channel 5 & 6 Sensitivity Control

Address (hex): 04h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch6HL	Ch6M[2:0]			Ch5HL	Ch5M[2:0]		

#### Description

The sensitivity of channel 5 and 6 are adjustable by Sensitivity\_3 register. ChxM[2:0] allows various middle sensitivity and also the high and low sensitivities are decided with ChxHL.

Bit name	Reset	Function
ChxM[2:0]	011	Middle sensitivity T (= thickness of PC) @Cs = 0pF <div style="display: flex; justify-content: space-between;"> <div>             000: 14~16T              001: 12~14T              010: 10~12T              011: 08~10T           </div> <div>             100: 7~9T              101: 6~8T              110: 5~7T              111: 3~5T           </div> </div>
ChxHL	1	High and Low sensitivity selection for channel x 0: $HS = MS - (MS * 0.2)$ $LS = MS + (MS * 0.2)$ 1: $HS = MS - (MS * 0.3)$ $LS = MS + (MS * 0.3)$

### Sensitivity4

### Channel 7 & 8 Sensitivity Control

Address (hex): 05h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch8HL	Ch8M[2:0]			Ch7HL	Ch7M[2:0]		

#### Description

The sensitivity of channel 7 and 8 are adjustable by Sensitivity\_4 register. ChxM[2:0] allows various middle sensitivity and also the high and low sensitivities are decided with ChxHL.

Bit name	Reset	Function
ChxM[2:0]	011	Middle sensitivity T (= thickness of PC) @Cs = 0pF <div style="display: flex; justify-content: space-between;"> <div>             000: 14~16T              001: 12~14T              010: 10~12T              011: 08~10T           </div> <div>             100: 7~9T              101: 6~8T              110: 5~7T              111: 3~5T           </div> </div>
ChxHL	1	High and Low sensitivity selection for channel x 0: $HS = MS - (MS * 0.2)$ $LS = MS + (MS * 0.2)$ 1: $HS = MS - (MS * 0.3)$ $LS = MS + (MS * 0.3)$

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### Sensitivity5

### Channel 9 & 10 Sensitivity Control

Address (hex): 06h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch10HL		Ch10M[2:0]		Ch9HL		Ch9M[2:0]	

#### Description

The sensitivity of channel 9 and 10 are adjustable by Sensitivity\_5 register. ChxM[2:0] allows various middle sensitivity and also the high and low sensitivities are decided with ChxHL.

Bit name	Reset	Function
ChxM[2:0]	011	Middle sensitivity T (= thickness of PC) @Cs = 0pF <div><div><div>000: 14~16T</div><div>001: 12~14T</div><div>010: 10~12T</div><div>011: 08~10T</div></div><div><div>100: 7~9T</div><div>101: 6~8T</div><div>110: 5~7T</div><div>111: 3~5T</div></div></div>
ChxHL	1	High and Low sensitivity selection for channel x 0: HS = MS - (MS * 0.2) LS = MS + (MS * 0.2) 1: HS = MS - (MS * 0.3) LS = MS + (MS * 0.3)

### Sensitivity6

### Channel 11 & 12 Sensitivity Control









Address (hex): 07h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch12HL		Ch12M[2:0]		Ch11HL		Ch11M[2:0]	

#### Description

The sensitivity of channel 11 and 12 are adjustable by Sensitivity\_6 register. ChxM[2:0] allows various middle sensitivity and also the high and low sensitivities are decided with ChxHL.

Bit name	Reset	Function	
ChxM[2:0]	011	Middle sensitivity T (= thickness of PC) @Cs = 0pF	
		 000: 14~16T	 100: 7~9T
		 001: 12~14T	 101: 6~8T
		 010: 10~12T	 110: 5~7T
		 011: 08~10T	 111: 3~5T
ChxHL	1	High and Low sensitivity selection for channel x	
		0: HS = MS – (MS * 0.2) LS = MS + (MS * 0.2)	
		1: HS = MS – (MS * 0.3) LS = MS + (MS * 0.3)	

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8.3 General Control Register1

#### CTRL1 TSM12 General Control Register1

Address (hex): 08h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
MS	FTC[1:0]		ILC[1:0]		RTC[2:0]		

#### Description

The calibration speed just after power on reset is very high during the time which is defined by FTC[1:0] to have a good adoption against unstable external environment.

Bit name	Reset	Function
MS	0	Mode Selection 0: auto alternate (fast/slow) mode 1: fast mode
FTC[1:0]	01	First Touch Control Below time stands on VDD = 3V / Rb = 300KΩ 00: 5 sec 01: 10 sec 10: 15 sec 11: 20 sec
ILC[1:0]	00	Interrupt Level Control 00: Interrupt is on middle or high output. 01: Interrupt is on low or middle or high output. 10: Interrupt is on middle or high output. 11: Interrupt is on high output.
RTC[2:0]	011	Response Time Control Response period = RTC[2:0] + 2

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8.4 General Control Register2

**CTRL2**      TSM12 General Control Register2

Address (hex): 09h

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0	0	0	0	SRST	SLEEP	1	1

#### Description

All the digital blocks except analog and I2C block are reset when SRST is set. The SLEEP function allows getting very low current consumption when it is set. But the response time will be longer than normal operation. The bit0 and bit1 must be written with 0b'11 by host MCU.

Bit name	Reset	Function
SRST	0	Software Reset 0: Disable Software Reset 1: Enable Software Reset
SLEEP	1	Sleep Mode Enable 0: Disable Sleep Mode 1: Enable Sleep Mode
Bit[1:0]	XX	These bits must be written by 0b'11 during a system initialize phase. (refer to the chapter 9 "initialize flow example")

### 8.5 Channel Reference Reset Control Register

#### Ref\_rst1

#### Channel1~8 Reference Reset Control

Address (hex): 0Ah

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch8	Ch7	Ch6	Ch5	Ch4	Ch3	Ch2	Ch1

#### Description

The reference value of each channel will be renewing when Chx is set.

Bit name	Reset	Function
Chx	1	0: Disable reference reset 1: Enable reference reset
Ch1	0	0: Disable reference reset 1: Enable reference reset

#### Ref\_rst2

#### Channel9~12 Reference Reset Control

Address (hex): 0Bh

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0	0	0	0	Ch12	Ch11	Ch10	Ch9

#### Description

The reference value of each channel will be renewing when Chx is set.

Bit name	Reset	Function
Chx	1	0: Disable reference reset 1: Enable reference reset



## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8.6 Channel 1~8 Sensing Control Register

**Ch\_hold1**

**Channel 1 ~ 8 Hold Enable Register**

Address (hex): 0Ch

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch8	Ch7	Ch6	Ch5	Ch4	Ch3	Ch2	Ch1

#### Description

The operation of each channel is independently available to control. A channel doesn't be worked and the calibration is paused when it is set.

Bit name	Reset	Function
Chx	1	0: Enable operation (sensing + calibration) 1: Hold operation (No sensing + Stop calibration)
Ch1	0	0: Enable operation (sensing + calibration) 1: Hold operation (No sensing + Stop calibration)

### 8.7 Channel 9~12 Sensing Control Register

**Ch\_hold2**

**Channel 9 ~ 12 Hold Enable Register**

Address (hex): 0Dh

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0	0	0	0	Ch12	Ch11	Ch10	Ch9

#### Description

The operation of each channel is independently available to control. A channel doesn't be worked and the calibration is paused when it is set.

Bit name	Reset	Function
CEx	1	0: Enable operation (sensing + calibration) 1: Hold operation (No sensing + Stop calibration)

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8.8 Channel 1~8 Calibration Control Register

Cal\_hold1

Channel 1 ~ 8 Calibration Enable Register

Address (hex): 0Eh

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
Ch8	Ch7	Ch6	Ch5	Ch4	Ch3	Ch2	Ch1

#### Description

The calibration of each channel is independently available to control. Each channel is working even if a bit is set.

Bit name	Reset	Function
Chx	0	0: Enable reference calibration (sensing + calibration) 1: Disable reference calibration (sensing + No calibration)

### 8.9 Channel 9~12 Calibration Control Register

Cal\_hold2

Channel 9 ~ 12 Calibration Enable Register

Address (hex): 0Fh

Type: R/W

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0	0	0	0	Ch12	Ch11	Ch10	Ch9

#### Description

The calibration of each channel is independently available to control. Each channel is working even if a bit is set.

Bit name	Reset	Function
Chx	0	0: Enable reference calibration (sensing + calibration) 1: Disable reference calibration (sensing + No calibration)

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 8.10 Output Register

#### Output1 Channel 1 ~ 4 Output Register

Address (hex): 10h

Type: R

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
OUT4[1:0]		OUT3[1:0]		OUT2[1:0]		OUT1[1:0]	

#### Description

The each channel output of TSM12 is compressed with 2 bits. It has 3 level output information that is low, middle and high.

Bit name	Reset	Function
OUT4[1:0]	00	Output of channel 4 00: No output 01: low output 10: middle output 11: high output
OUT3[1:0]	00	Output of channel 3 00: No output 01: low output 10: middle output 11: high output
OUT2[1:0]	00	Output of channel 2 00: No output 01: low output 10: middle output 11: high output
OUT1[1:0]	00	Output of channel 1 00: No output 01: low output 10: middle output 11: high output

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## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### Output2

### Channel 5 ~ 8 Output Register

Address (hex): 11h

Type: R

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
OUT8[1:0]		OUT7[1:0]		OUT6[1:0]		OUT5[1:0]	

### Description

The each channel output of TSM12 is compressed with 2 bits. It has 3 level output information that is low, middle and high.

Bit name	Reset	Function
OUT8[1:0]	00	Output of channel 8 00: No output 01: low output 10: middle output 11: high output
OUT7[1:0]	00	Output of channel 7 00: No output 01: low output 10: middle output 11: high output
OUT6[1:0]	00	Output of channel 6 00: No output 01: low output 10: middle output 11: high output
OUT5[1:0]	00	Output of channel 5 00: No output 01: low output 10: middle output 11: high output

## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### Output3

### Channel 9~ 12 Output Register

Address (hex): 12h

Type: R

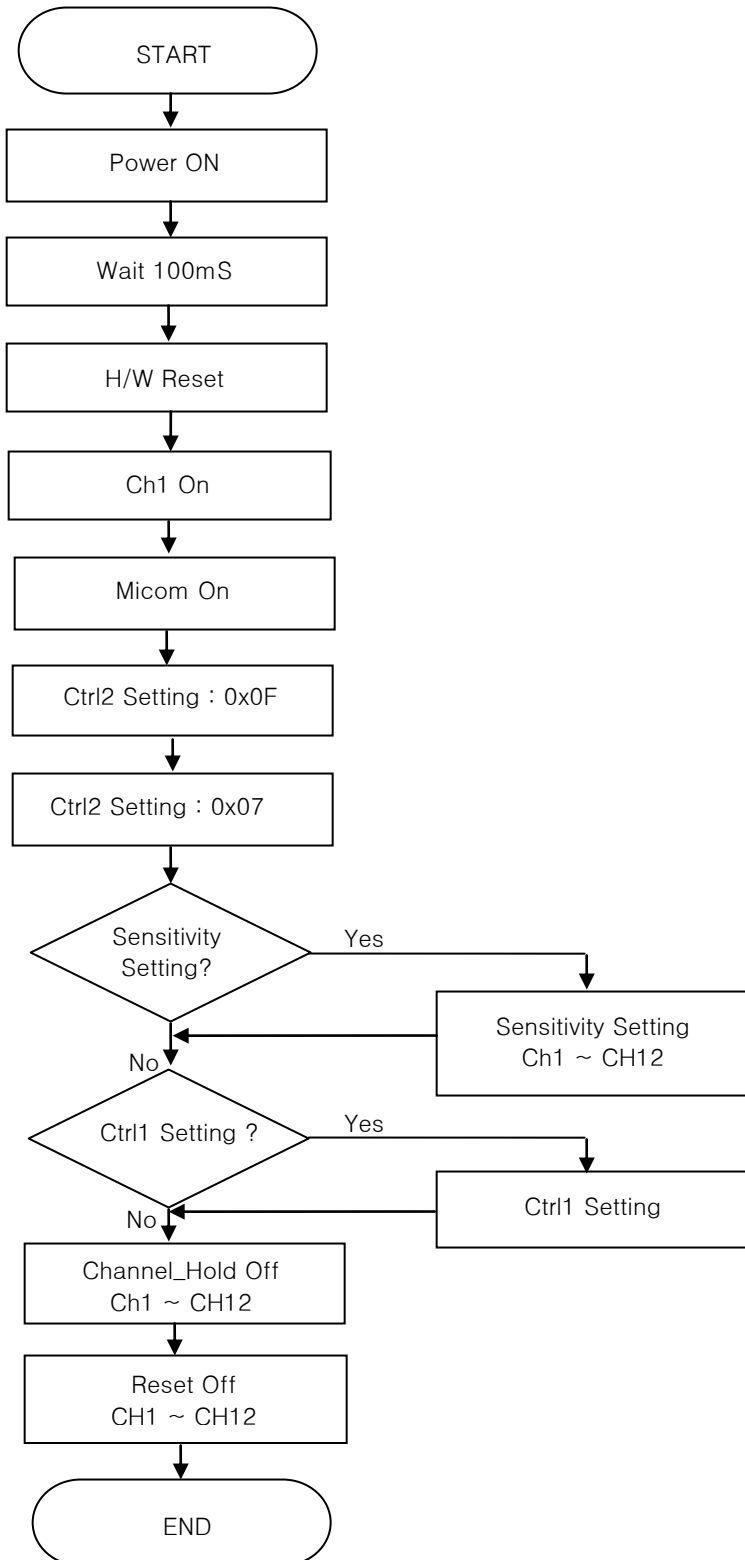
Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
OUT12[1:0]		OUT11[1:0]		OUT10[1:0]		OUT9[1:0]	

### Description

The each channel output of TSM12 is compressed with 2 bits. It has 3 level output information that is low, middle and high.

Bit name	Reset	Function
OUT12[1:0]	00	Output of channel 12 00: No output 01: low output 10: middle output 11: high output
OUT11[1:0]	00	Output of channel 11 00: No output 01: low output 10: middle output 11: high output
OUT10[1:0]	00	Output of channel 10 00: No output 01: low output 10: middle output 11: high output
OUT9[1:0]	00	Output of channel 9 00: No output 01: low output 10: middle output 11: high output

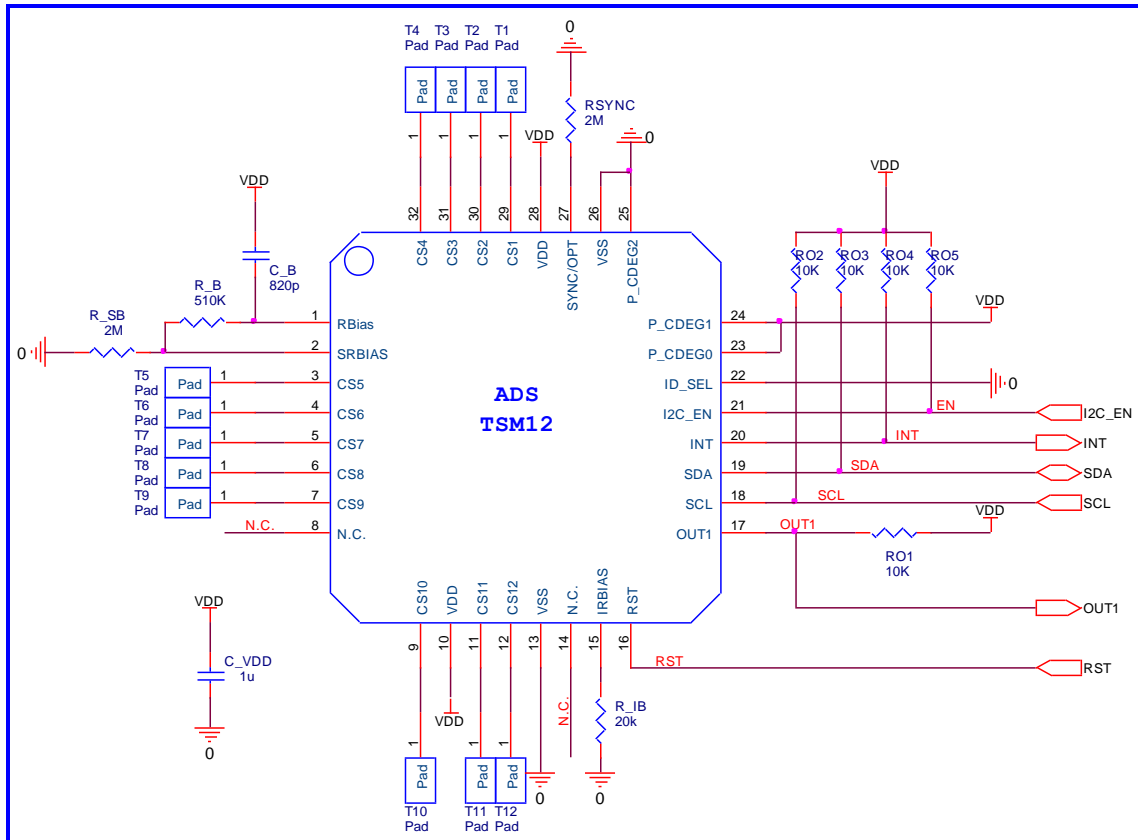
### 9 Recommended TSM12 Initialize Flow (Example)



## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 10 Recommended Circuit Diagram

#### 10.1 Application Example in clean power environment



TSM12 Application Example Circuit (Clean power environment)

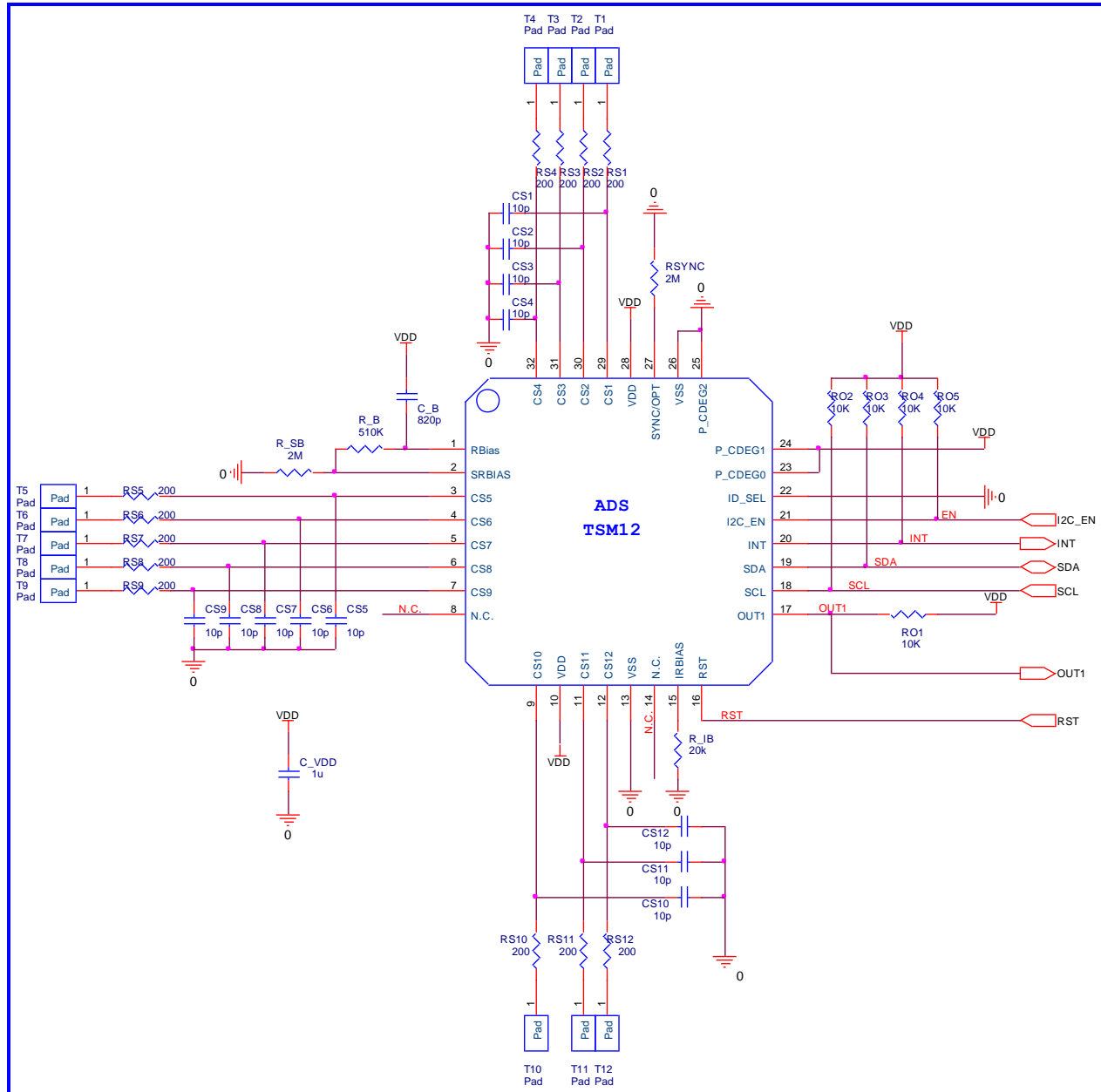
- In PCB layout, R\_B should not be placed on touch pattern. If not, C\_B has to be connected. The R\_B pattern should be routed as short as possible.
- The CS patterns also should be routed as short as possible and the width of line might be about 0.25mm.
- The capacitor that is between VDD and GND is an obligation. It should be located as close as possible from TSM12.
- The CS pattern routing should be formed by bottom metal (opposite metal of touch PAD).
- The empty space of PCB must be filled with GND pattern to strengthen GND pattern and to prevent external noise from interfere with sensing frequency.
- The TSM12 is reset if RST Pin is high. (See 6.5 Reset implementation chapter)
- The TSM12 is working with single output mode if the SYNC/OPT pin is high and it will be in multi output mode when it's low. The resistor which is connected with GND should be connected with SYNC pin when the application is required over two TSM12 devices (Multi output mode).

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## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

### 10.2 Application Example in noisy environment



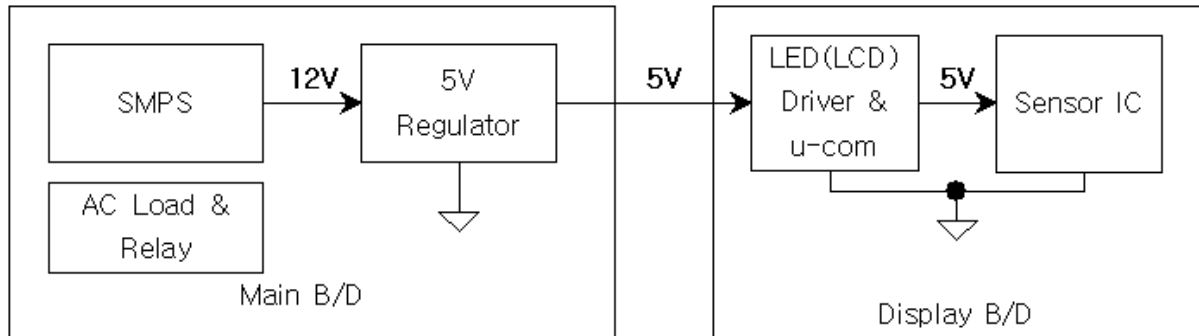
TSM12 Application Example Circuit (Noisy environment)

- The VDD periodic voltage ripple over 50mV and the ripple frequency is lower than 10 kHz can cause wrong sensitivity calibration. To prevent above problem, power (VDD, GND) line of touch circuit should be separated from other circuit. Especially LED driver power line or digital switching circuit power line certainly should be treated to be separated from touch circuit.
- The smaller R\_B is recommended in noisy environments.



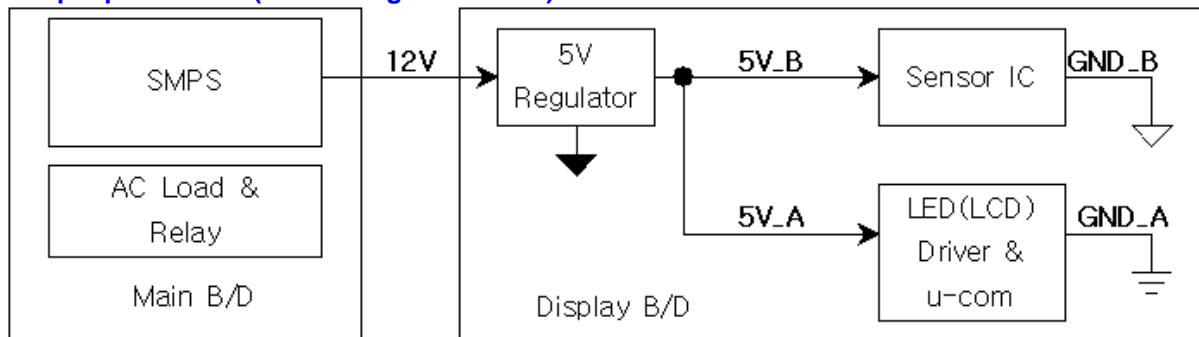
### 10.3 Example – Power Line Split Strategy PCB Layout

#### A. Not split power Line (Bad power line design)

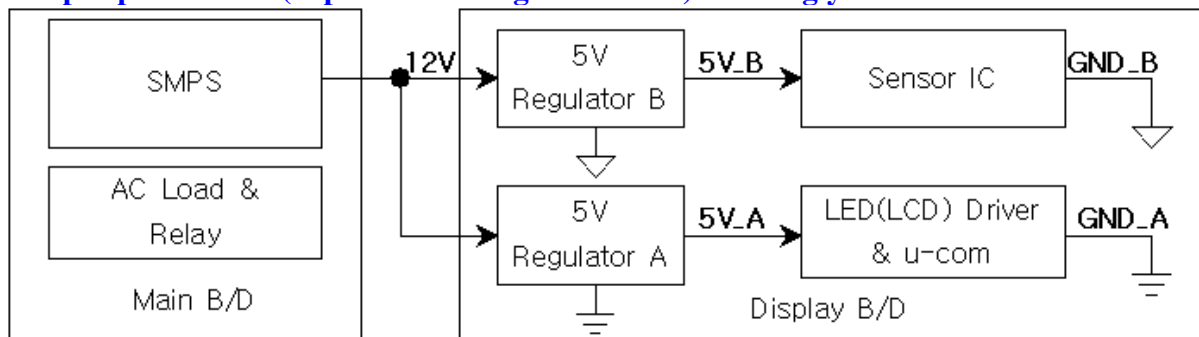


- ✦ The noise that is generated by AC load or relay can be loaded at 5V power line.
- ✦ A big inductance might be appeared in case of the connection line between main board and display board is too long, moreover the voltage ripple could be generated by LED (LCD) display driver at VDD (5V).

#### B. Split power Line (One 5V regulator used) – Recommended

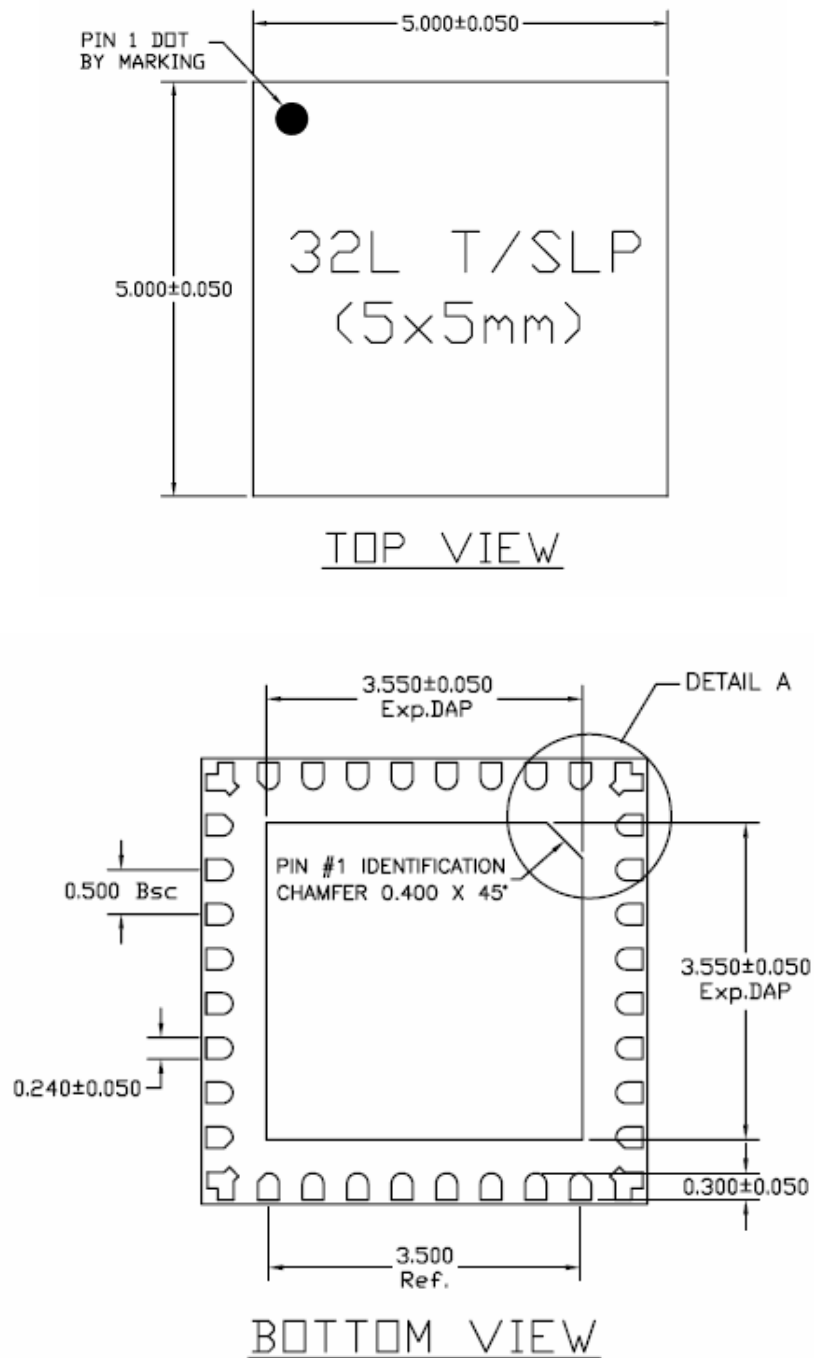


#### C. Split power Line (Separated 5V regulator used) – Strongly recommended



### 11 MECHANICAL DRAWING

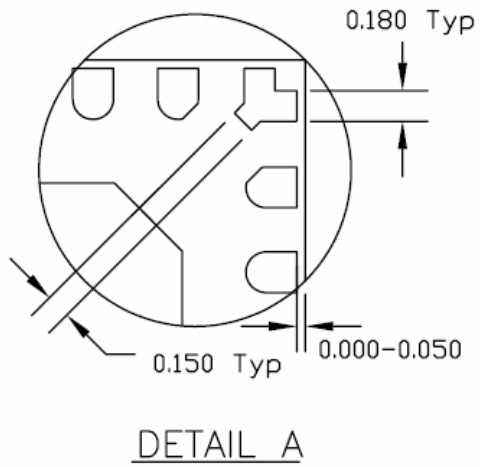
#### 11.1 TSM12 - 32QFN package



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## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)



SIDE VIEW

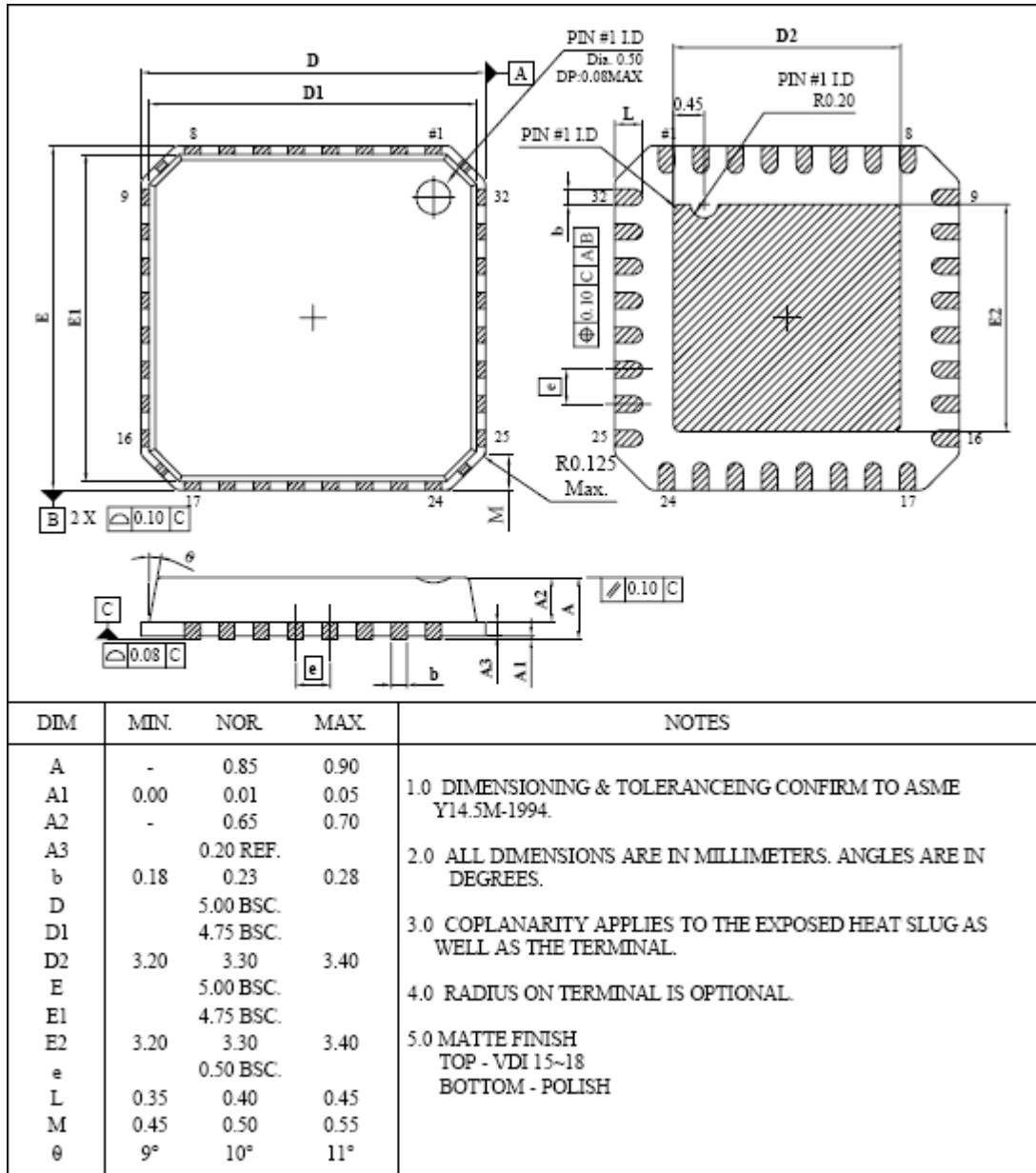
A	QFN	
	MAX.	0.900
	NOM.	0.850
	MIN.	0.800

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## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

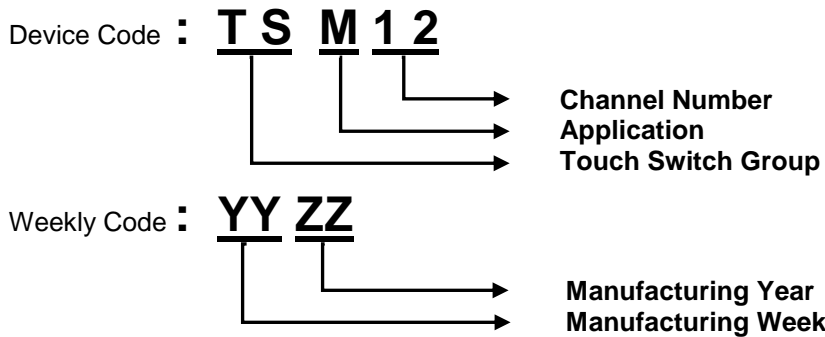
### 11.2 TSM12 - 32MLF package



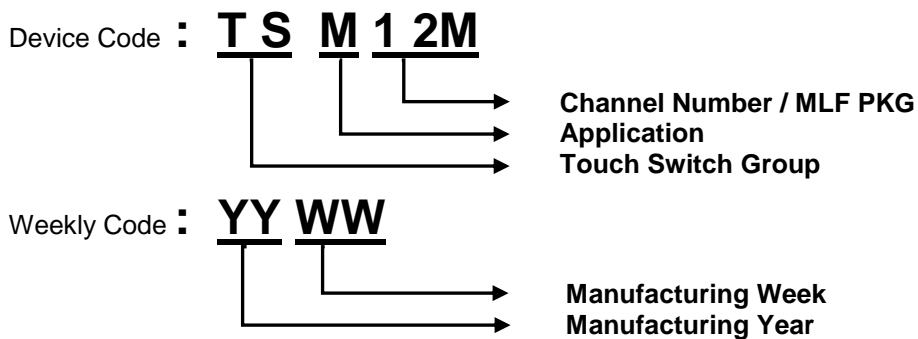
NOTE: Dimensions are in millimeters

### 12 MARKING DESCRIPTION

#### 12.1 TSM12 – 32QFN package



#### 12.2 TSM12 – 32MLF package



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## TSM12 (12-CH Auto Sensitivity Calibration Capacitive Touch Sensor)

NOTES:

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